

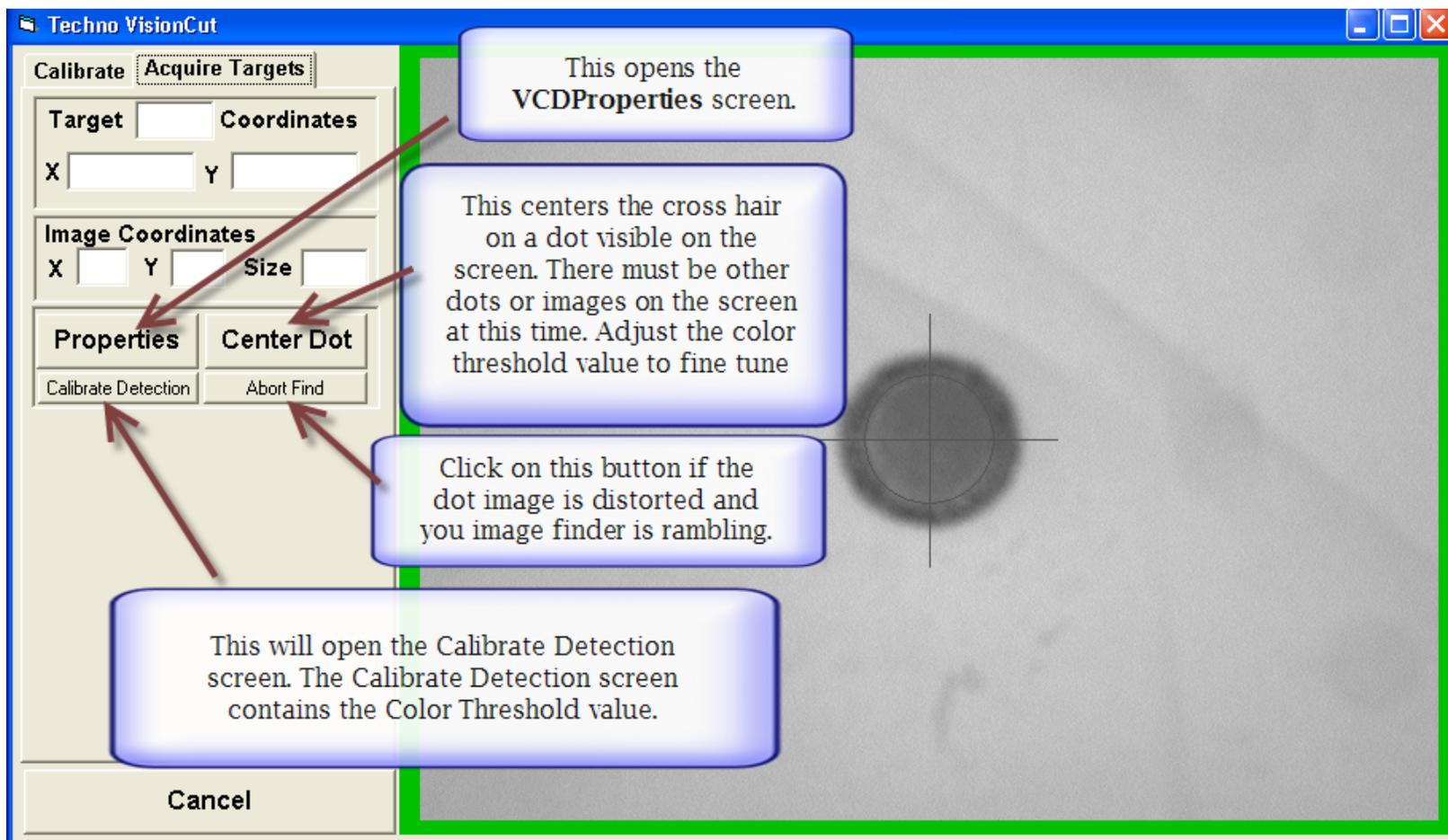
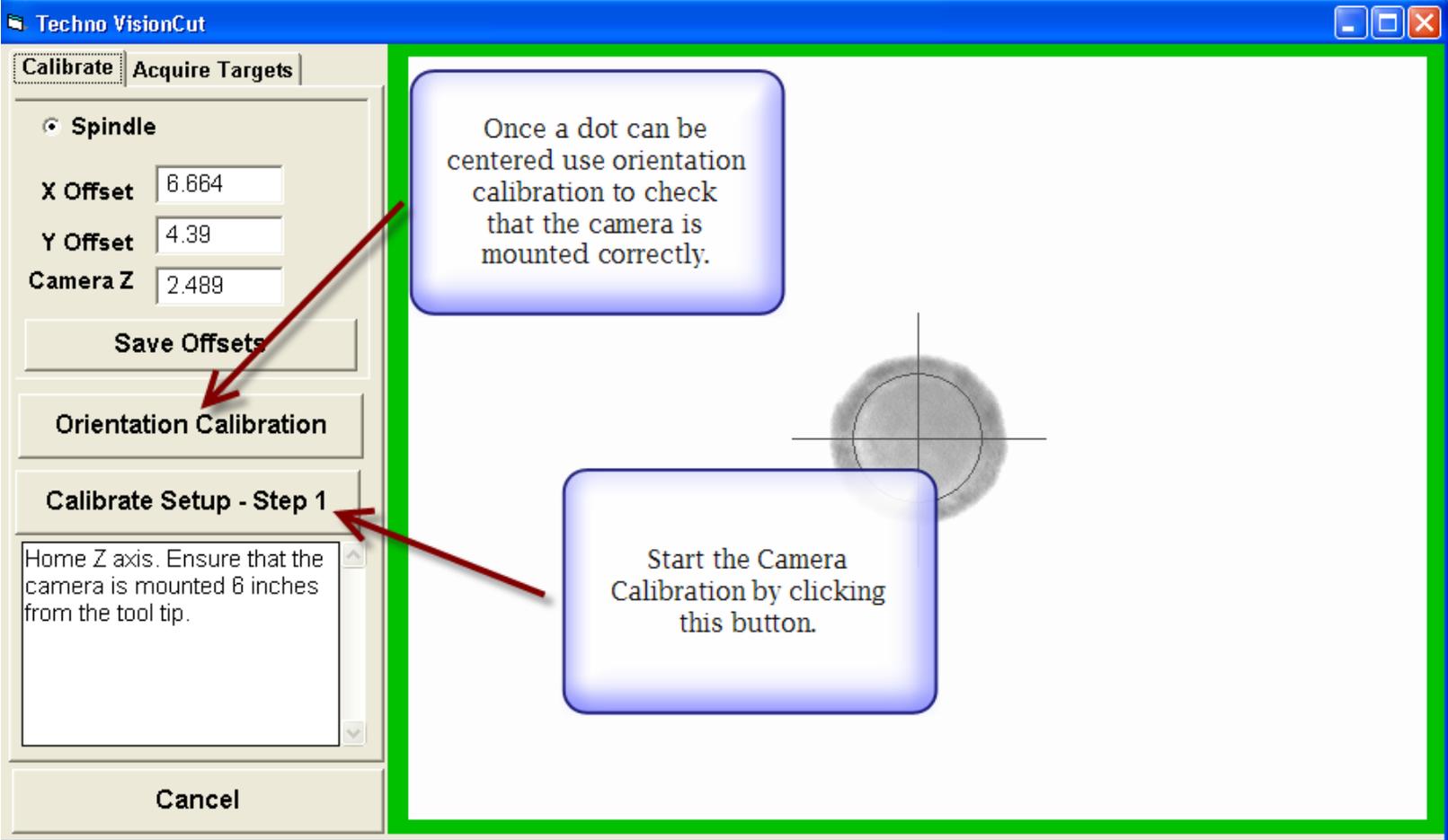
# Techno Vision System Build 413

Installation and calibration remains essentially the same for 413 as in 412.

Please refer to document

0412\_Techn Vision Systems Manual-3.pdf , located on the techno cd for these instructions.

This document will explain some of the features in build number 413 and show how to optimize the the vision system operation



**Calibrate Detecion**

Calibrate Detection

Y Prop. Gain

Y Deriv. Gain

X Prop. Gain

X Deriv. Gain

Flex Delay

Enable Vision Debugging

Y Allowed Error

X Allowed Error

Color Threshold

Show Result

**Calibrate Detection:** These values control how much power the motors receive when they move to locate the dot. If the values are too high the camera will over travel and miss the dot. These values are good default values. **Flex Delay** is the time the camera waits before it captures the dot image. This value is in milliseconds.



Apply

Close

**Calibrate Detection**

Calibrate Detection

Y Prop. Gain

Y Deriv. Gain

X Prop. Gain

X Deriv. Gain

Flex Delay

Enable Vision Debugging

Y Allowed Error

X Allowed Error

Color Threshold

When calibrating Threshold, you must click apply before Show.

Show Result

**Color Threshold:** This value will depend on the value of Auto Reference value set in VCD properties. Auto Reference should be set between 35 and 55.

The higher the Color Threshold value the darker the image will get. Adjust this value until a clear image of the dot is visible.



Apply

Close

# Default Settings For Camera

The screenshot displays the 'Calibrate Detection' window in the Techno VisionCut software. The window contains several input fields for calibration parameters:

- Y Prop. Gain: 10
- Y Deriv. Gain: 1.7
- X Prop. Gain: 10
- X Deriv. Gain: 1.7
- Flex Delay: 20
- Color Threshold: 400

Additional settings include 'Y Allowed Error' and 'X Allowed Error', both set to 0, and an unchecked 'Enable Vision Debugging' checkbox. A 'Show Result' button is located below the Color Threshold field. The main display area shows a black circle on a white background.

Two callout boxes provide additional information:

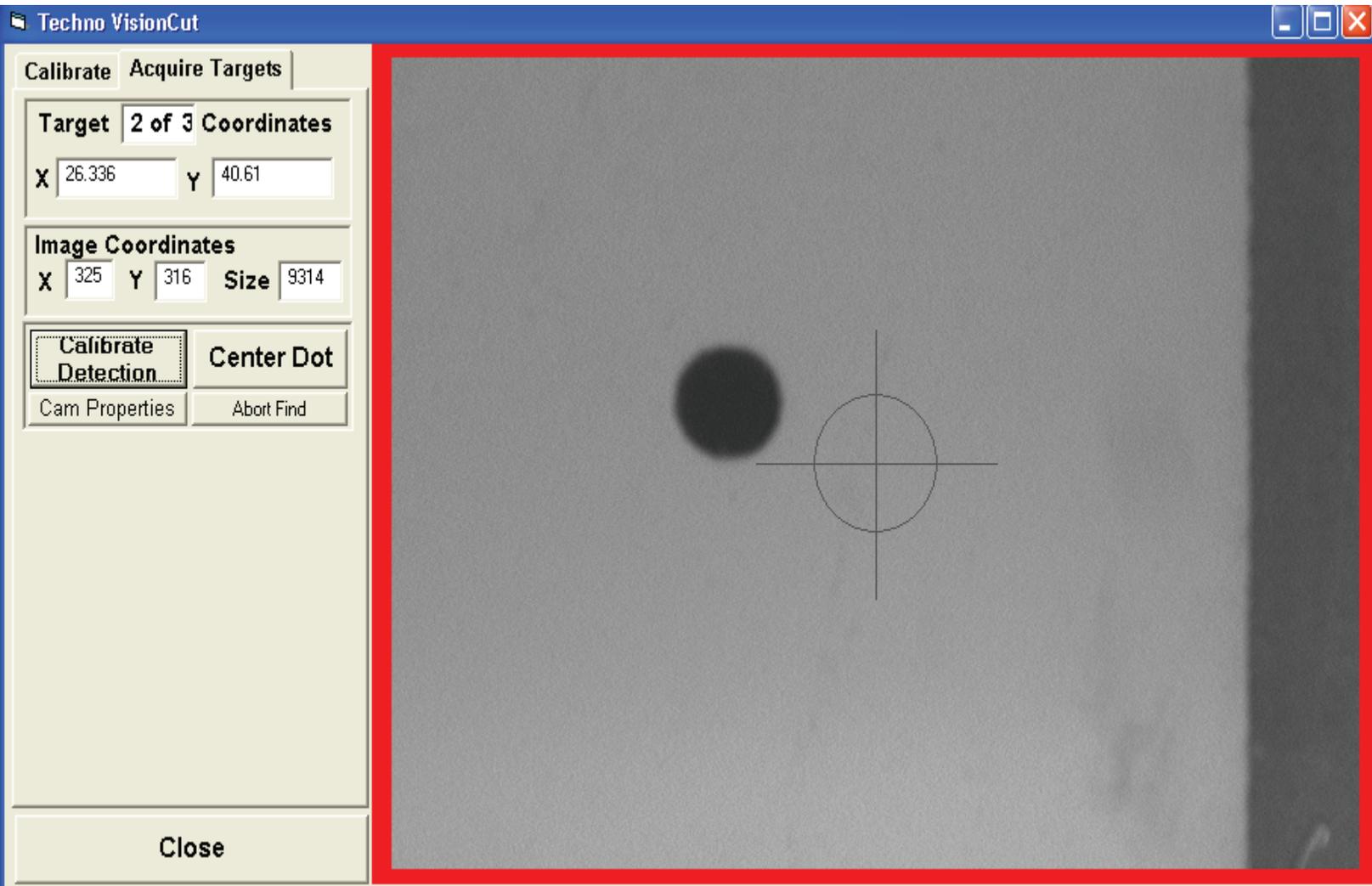
- A blue box states: "These are the ideal default values for the camera. Some tweaking may be necessary."
- A white box lists the default values: Y Prop. Gain- 10, Y Derriv. Gain- 1.7, X Prop. Gain- 10, Y Derriv Gain- 1.7, Flex Delay- 20, Color Threshold 400, Y Allowed Error- 0, and X allowed Error- 0.

At the bottom of the window, there are 'Apply' and 'Close' buttons. The background shows a control panel with directional buttons for X+, X-, Y+, Y-, Z+, Z-, A+, and A-.

Another callout box over the control panel shows: Exposure: Auto and Auto Reference Parameter: 40.

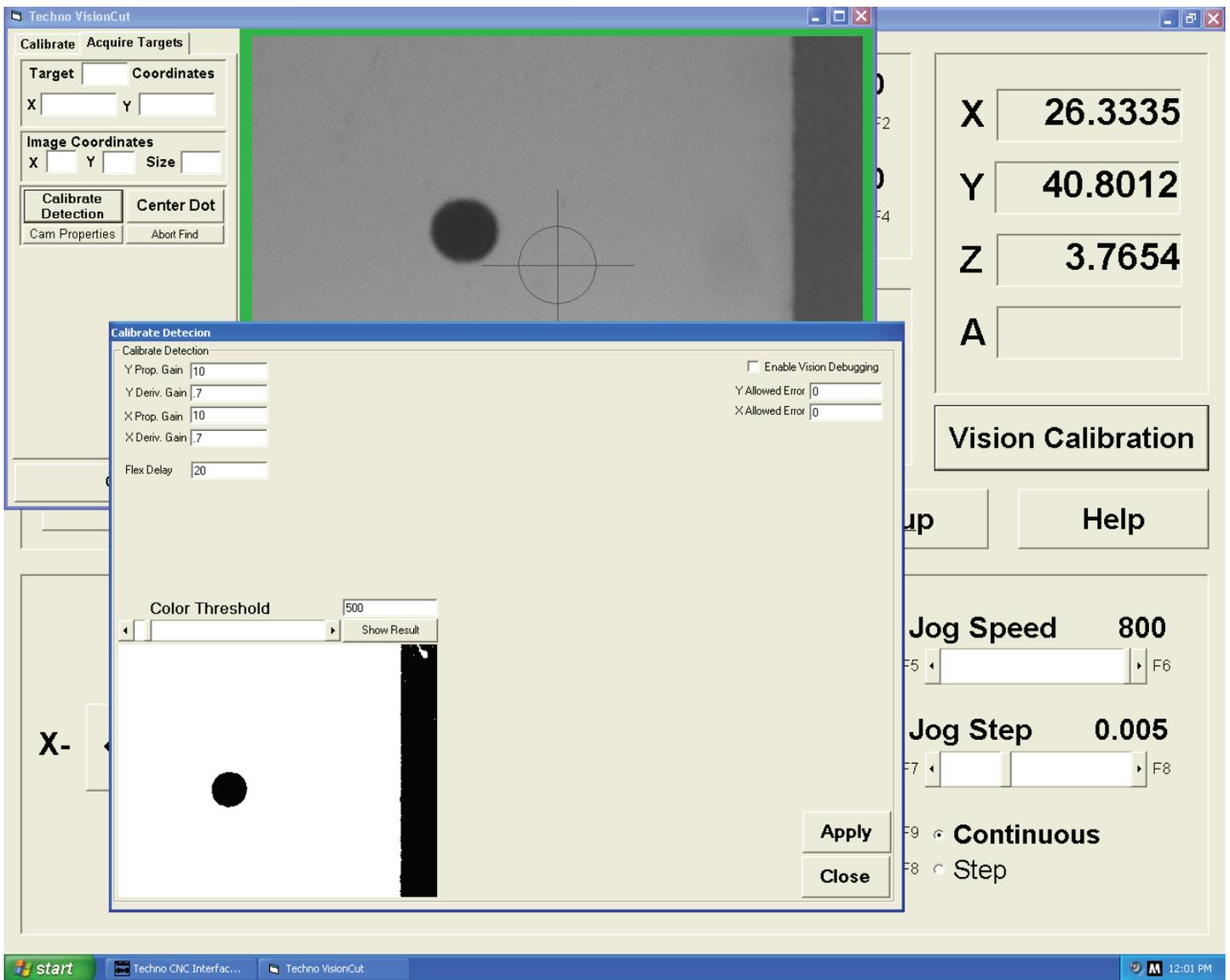
The Windows taskbar at the bottom shows the start button, search results, and open applications including Vision System, Techno CNC Interfac..., Techno VisionCut, and McAfee SecurityCent... The 'Setup' window is also partially visible on the right side.

# Fault Finding/Optmizing the Vision System

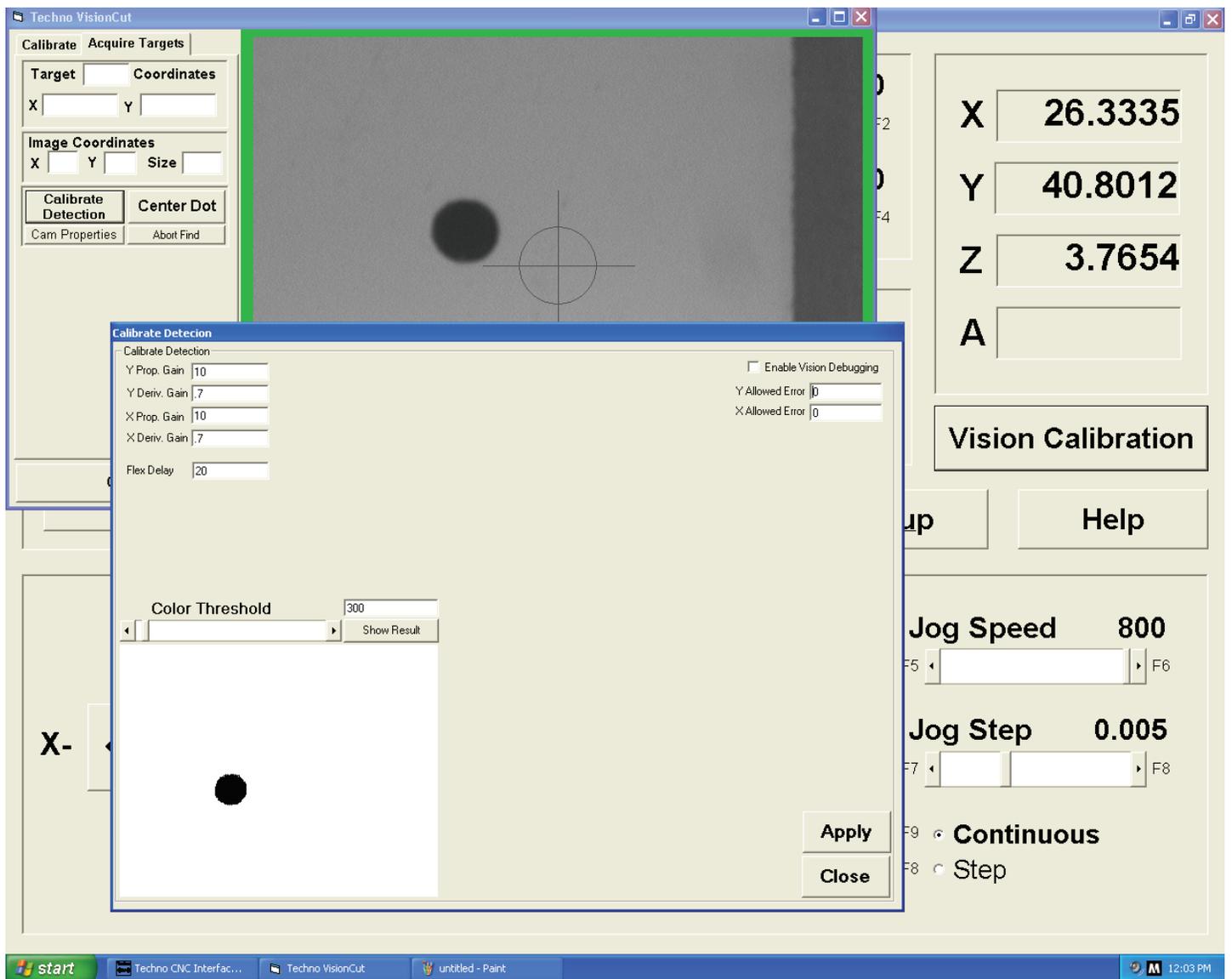


In the above situation it is possible that the vision system will not find the dot. It may start to ramble or it may hover between the dot and the dark line on the right.

This can be fixed to some degree by adjusting the color threshold in the Calibrate Dection screen.



When *show result* is clicked an image of what the camera sees appears on the screen. As you can see, there is a dark line on the right which is confusing the image recognition software. The Color Threshold needs to be adjusted until only the dot is visible.



With a reduced Color Threshold the dark line is ignored and the dot will be perfectly centered.